

LIAIR X3C-H

Compact UAV LiDAR System



The LiAir X3C-H is a new compact high-performance UAV LiDAR system. It adopts a new integrated design style and a built-in highresolution mapping camera, providing higher performance and convenient operation for power-line inspection, topographic surveying, agricultural and forest monitoring, and more.

Advantages

I Integrated Design

The operation interface is compact and convenient, with an unpluggable TF card and engineered data storage model that allows for one-touch operation and copying of laser and camera data.

I New Camera, providing ultra-clear picture quality

The built-in high-resolution mapping camera has been upgraded to 26 MP, providing ultraclear picture quality and enabling the creation of high-quality true-color point clouds and orthophotos for Photogrammetry. Additionally, the external camera interface allows for simultaneous mounting of infrared cameras and other camera types, making the LiAir X3C-H a versatile tool for a wide range of applications.

Handheld Accessories

Lightweight and quick-release design, one-button operation for efficient work. 3 hours of extra-long battery life. GNSS module with SLAM technology for signal-blocking resistance, enabling operation in indoor and outdoor spaces. Compatible with multiple fields such as forestry, mining surveying, power monitoring, and building facade surveying.



I Lightweight and easy to disassemble

The overall weight of the handheld part is 0.68 kg, and the ergonomic design allows for easy grip. The single battery has a battery life of 3 hours, and with one-button operation and installation, it can be used immediately after installation.

I High-precision fusion

From aerial (with GNSS signal) to indoor (without GNSS signal) operation in all spaces, with a flying platform and handheld kit, directly obtain ground point cloud data with absolute coordinates and airborne point cloud data, meeting the needs of multiple scenarios. The point cloud fusion accuracy can reach centimeter level.

I High-efficiency operation

3-5 cm super high accuracy, point density better than 10,000 pts/m², effective measurement range of 190 m (10% reflectivity), and an operation efficiency of up to 100,000 m² per hour.

I Multi-scene operation

With SLAM technology and GNSS module for accurate positioning, it can be used in areas without GNSS signal to generate accurate 3D point cloud models and rich features. It is suitable for multiple applications such as forestry, mining surveying, power monitoring, building scanning, and more.

Specifications

System Specificat	ions							
Detection Range		80 m @ 10% reflectivity 200 m @ 54% reflectivity 300 m @ 90% reflectivity			System Accuracy (Vertical) 5 cm @ 70m			
					Typical Flight Speed	5-10 m/s		
Weight		1.12 kg			Storage	256 GB TF Card		
Voltage		12~24 V			Power Consumption	24 W		
Operating Temperature		-20~50 °C			Storage Temperature	-30~60 °C	-30~60 °C	
Communication		WiFi						
LiDAR Sensor Para	ameters							
Wavelength		905 nm			Number of Channels	32		
Point Rate		Single Return: 640,000 pts/s Dual Return: 1,280,000 pts/s Triple Return: 1,920,000 pts/s			FOV	360° (Horizontal)×40.3° (Vertical)		
					Number of Returns	3		
Inertial Navigatio	n System							
GNSS		GPS, GLONASS, Galileo, BDS			Azimuth Accuracy	0.038°		
Attitude Accuracy		0.008°			IMU Data Frequency	200 Hz		
Camera Paramete	ers							
Pixels		26 MP			Image Resolution	6252×4168		
Focal Length		16 mm / 24 mm (Equiv. Focal Length)						
Software								
Control Software		GreenValley			Pre-processing	LiGeoreference		
Post-processing		LiDAR360 / LiPowerline (Optional)						
Compatible Platfo	orms							
DJI, Freefly, etc.								
Handheld Acc	essories							
System Parameter	rs							
Handheld Size	181.8×108×88 mm		Handheld Weight	Handheld Weight 0.68 kg (Including B		Voltage	15.2 V	
Battery Box Size	146×57×148 mm		Battery Capacity	5870 mAh A		Antenna	AT-106	
Single-Flight Continuous Operation Time	Maximum 55 mins		Battery Box Weight	Battery Box Weight 0.81 kg		Working Time of One Battery Block	3 h	
Applicable Environment	Applicable to multiple scenarios both indoors and outdoors							
Mapping Method								
Mapping Principle SLAM, PP		K-SLAM Real-Time Calculation		Not Si	ot Supported			
Data Results								
Absolute Accuracy	≤5 cm		Point Cloud Format	LAS, LiData				